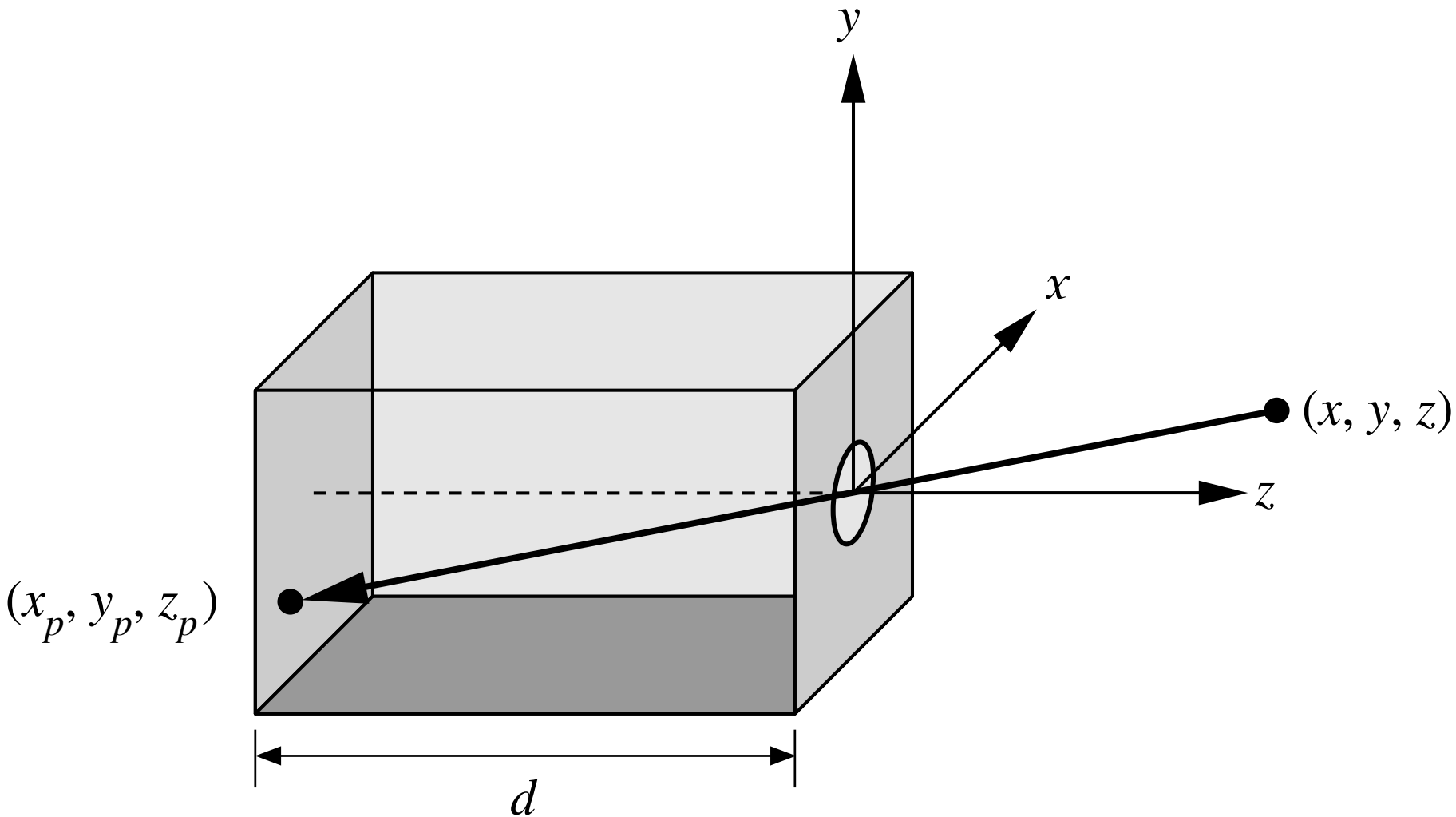
y
x
(x, y, z)
z
(x_p, y_p, z_p)
d