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# Implementation I

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# Objectives

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- Introduce basic implementation strategies
- Clipping
- Scan conversion



# Overview

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- At end of the geometric pipeline, vertices have been assembled into primitives
- Must clip out primitives that are outside the view frustum
  - Algorithms based on representing primitives by lists of vertices
- Must find which pixels can be affected by each primitive
  - Fragment generation
  - Rasterization or scan conversion



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# Required Tasks

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- Clipping
- Rasterization or scan conversion
- Transformations
- Some tasks deferred until fragement processing
  - Hidden surface removal
  - Antialiasing



# Rasterization Meta Algorithms

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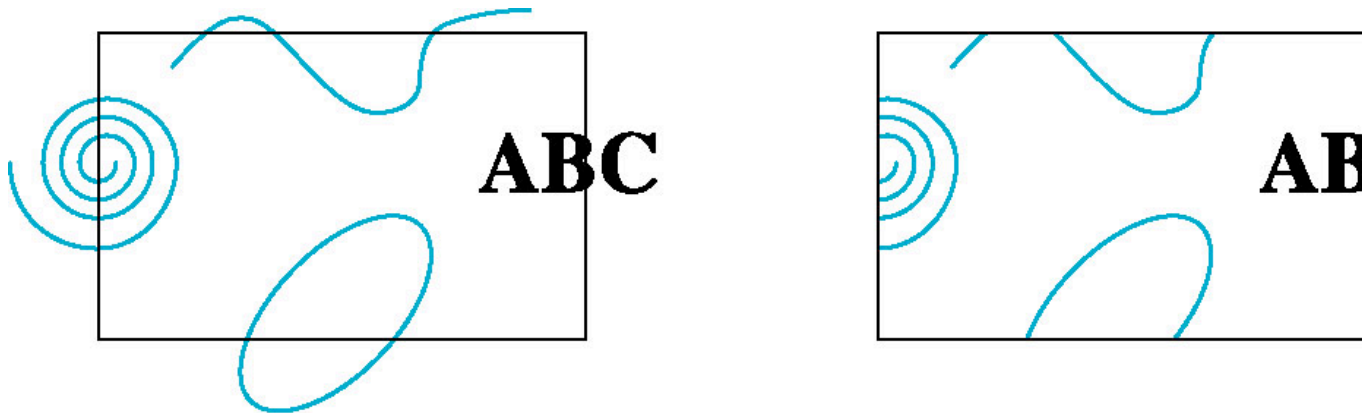
- Consider two approaches to rendering a scene with opaque objects
- For every pixel, determine which object that projects on the pixel is closest to the viewer and compute the shade of this pixel
  - Ray tracing paradigm
- For every object, determine which pixels it covers and shade these pixels
  - Pipeline approach
  - Must keep track of depths

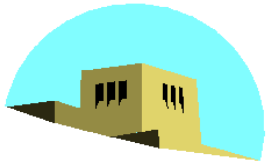


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# Clipping

- 2D against clipping window
- 3D against clipping volume
- Easy for line segments polygons
- Hard for curves and text
  - Convert to lines and polygons first

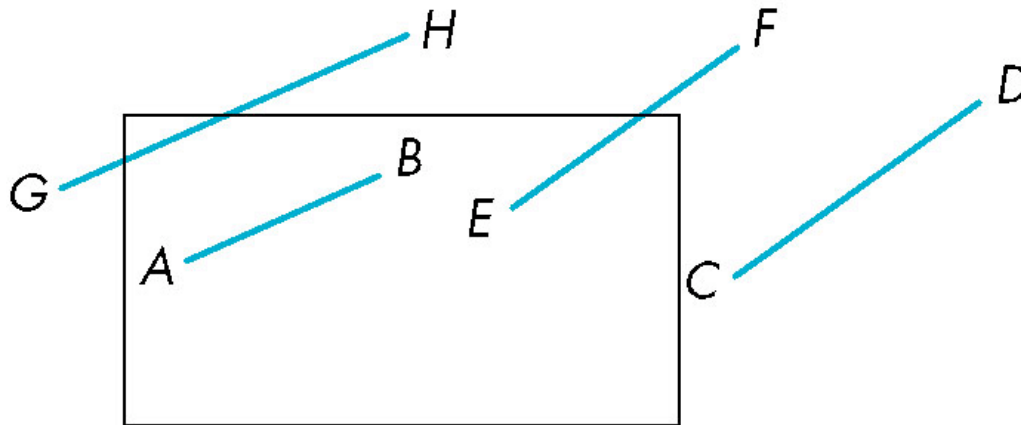




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# Clipping 2D Line Segments

- Brute force approach: compute intersections with all sides of clipping window
  - Inefficient: one division per intersection

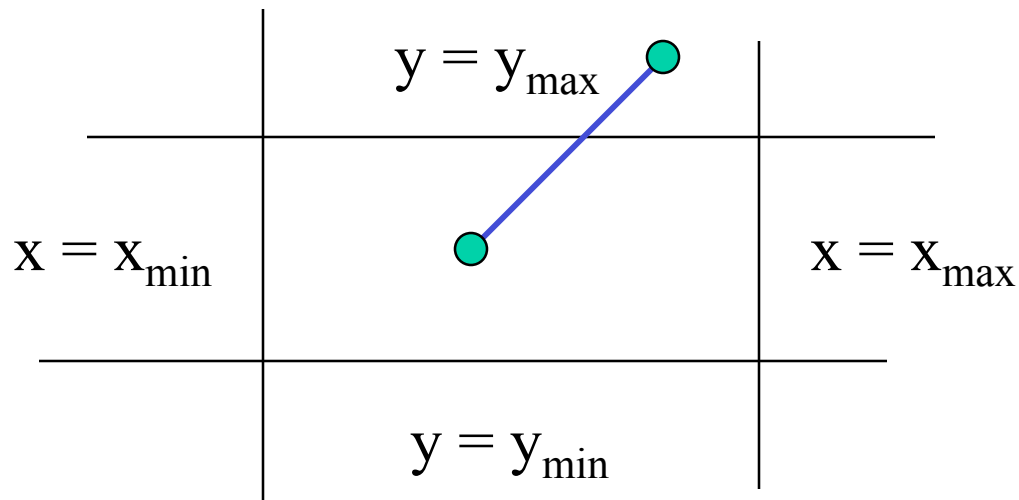




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# Cohen-Sutherland Algorithm

- Idea: eliminate as many cases as possible without computing intersections
- Start with four lines that determine the sides of the clipping window

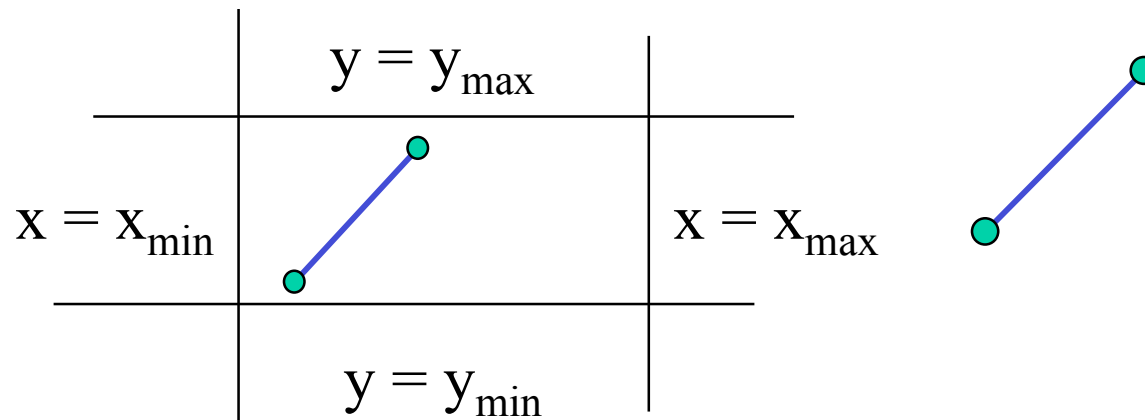






# The Cases

- Case 1: both endpoints of line segment inside all four lines
  - Draw (accept) line segment as is

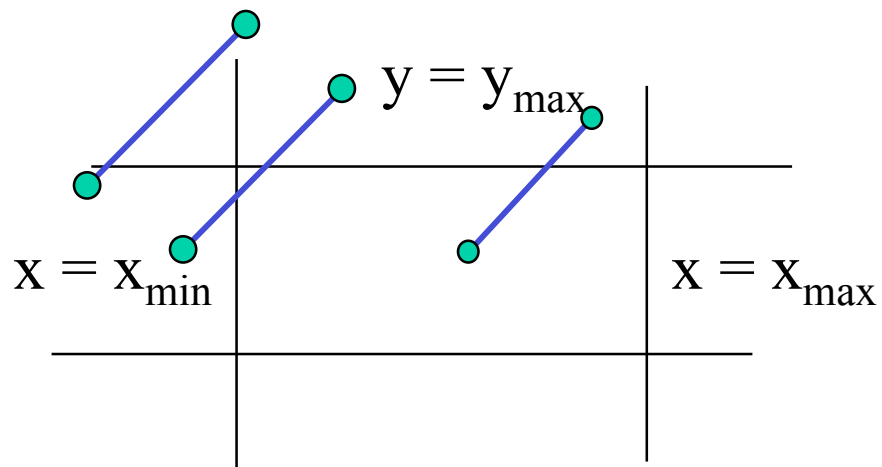


- Case 2: both endpoints outside all lines and on same side of a line
  - Discard (reject) the line segment



# The Cases

- Case 3: One endpoint inside, one outside
  - Must do at least one intersection
- Case 4: Both outside
  - May have part inside
  - Must do at least one intersection





# Defining Outcodes

- For each endpoint, define an outcode

$$b_0b_1b_2b_3$$

$b_0 = 1$  if  $y > y_{\max}$ , 0 otherwise

$b_1 = 1$  if  $y < y_{\min}$ , 0 otherwise

$b_2 = 1$  if  $x > x_{\max}$ , 0 otherwise

$b_3 = 1$  if  $x < x_{\min}$ , 0 otherwise

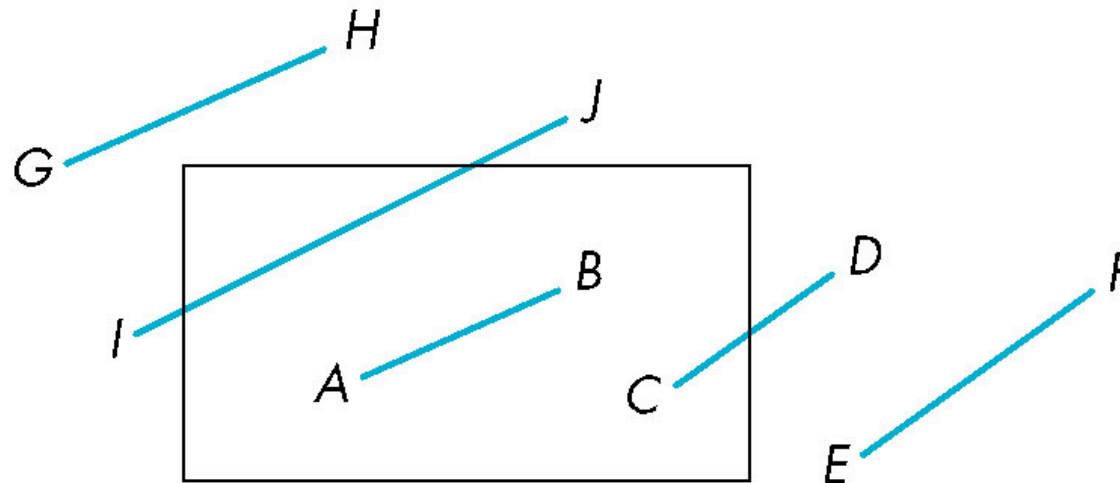
1001	1000	1010	$y = y_{\max}$
0001	0000	0010	
0101	0100	0110	$y = y_{\min}$
$x = x_{\min}$		$x = x_{\max}$	

- Outcodes divide space into 9 regions
- Computation of outcode requires at most 4 subtractions



# Using Outcodes

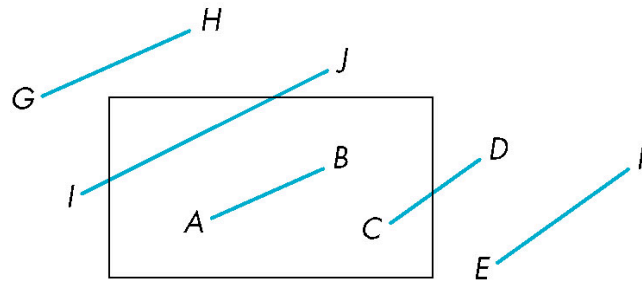
- Consider the 5 cases below
- AB:  $\text{outcode}(A) = \text{outcode}(B) = 0$ 
  - Accept line segment





# Using Outcodes

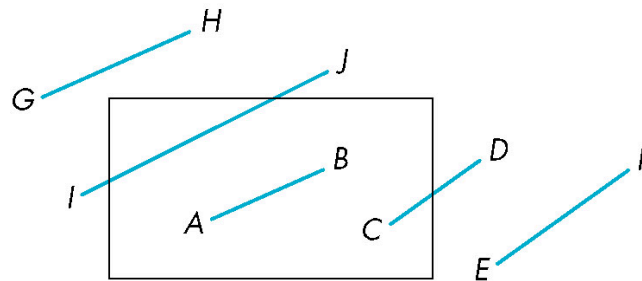
- CD: outcode (C) = 0, outcode(D)  $\neq$  0
  - Compute intersection
  - Location of 1 in outcode(D) determines which edge to intersect with
  - Note if there were a segment from A to a point in a region with 2 ones in outcode, we might have to do two interesections





# Using Outcodes

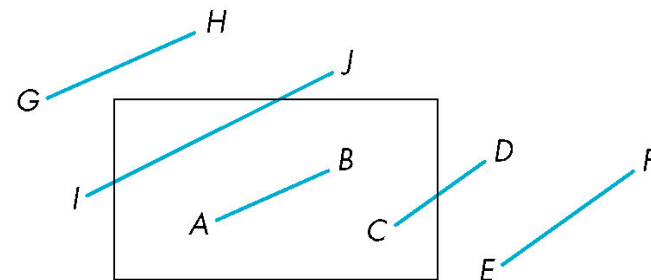
- EF: outcode(E) logically ANDed with outcode(F) (bitwise)  $\neq 0$ 
  - Both outcodes have a 1 bit in the same place
  - Line segment is outside of corresponding side of clipping window
  - reject





# Using Outcodes

- GH and IJ: same outcodes, neither zero but logical AND yields zero
- Shorten line segment by intersecting with one of sides of window
- Compute outcode of intersection (new endpoint of shortened line segment)
- Reexecute algorithm





# Efficiency

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- In many applications, the clipping window is small relative to the size of the entire data base
  - Most line segments are outside one or more side of the window and can be eliminated based on their outcodes
- Inefficiency when code has to be reexecuted for line segments that must be shortened in more than one step

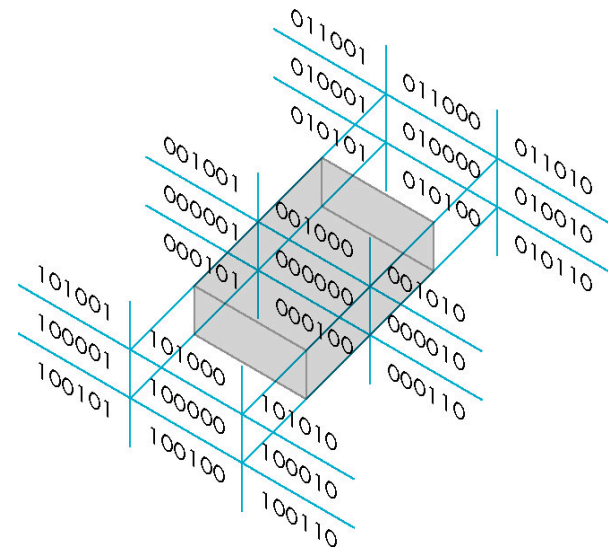
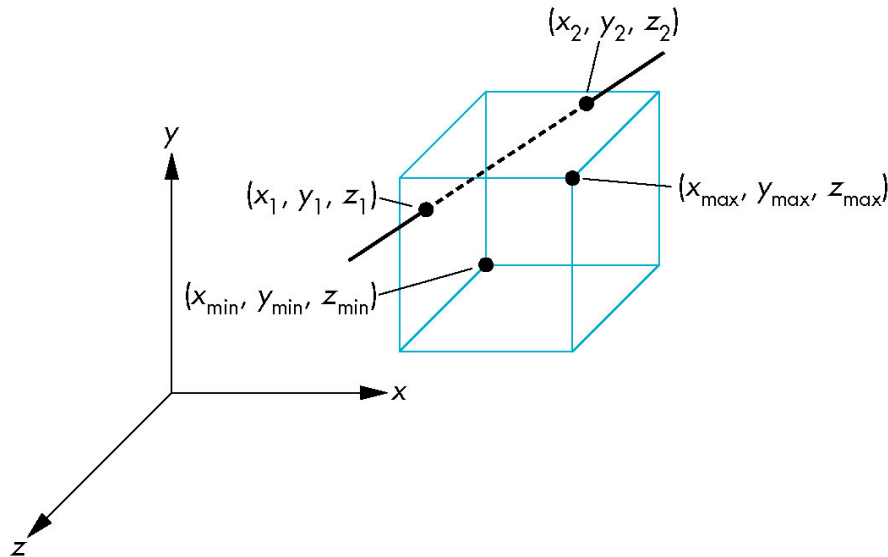




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# Cohen Sutherland in 3D

- Use 6-bit outcodes
- When needed, clip line segment against planes



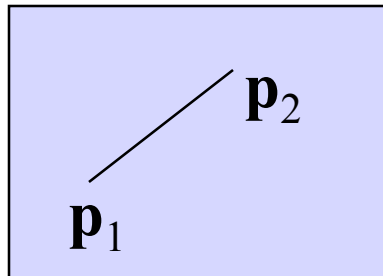


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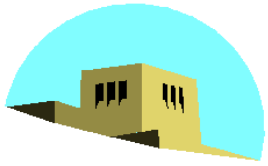
# Liang-Barsky Clipping

- Consider the parametric form of a line segment

$$\mathbf{p}(\alpha) = (1-\alpha)\mathbf{p}_1 + \alpha\mathbf{p}_2 \quad 1 \geq \alpha \geq 0$$



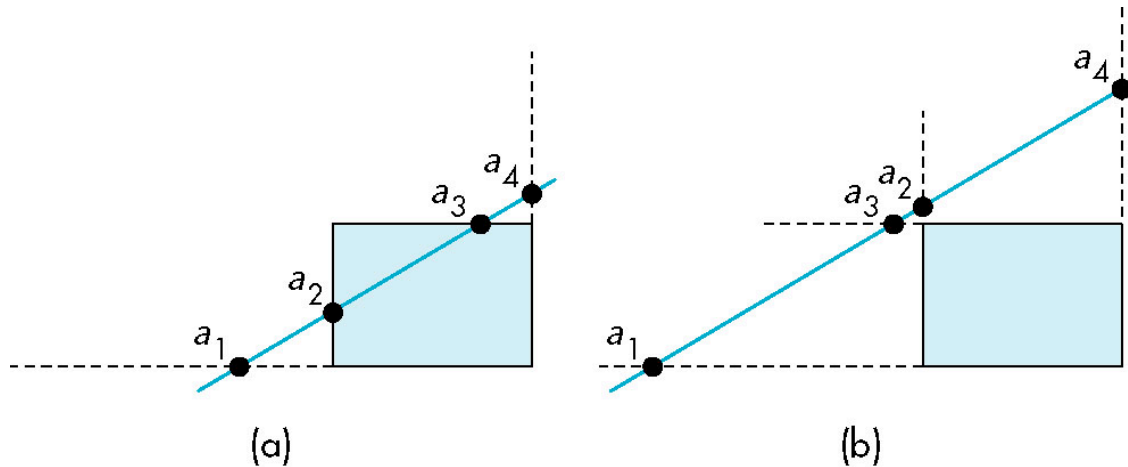
- We can distinguish between the cases by looking at the ordering of the values of  $\alpha$  where the line determined by the line segment crosses the lines that determine the window



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# Liang-Barsky Clipping

- In (a):  $\alpha_4 > \alpha_3 > \alpha_2 > \alpha_1$ 
  - Intersect right, top, left, bottom: shorten
- In (b):  $\alpha_4 > \alpha_2 > \alpha_3 > \alpha_1$ 
  - Intersect right, left, top, bottom: reject





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# Advantages

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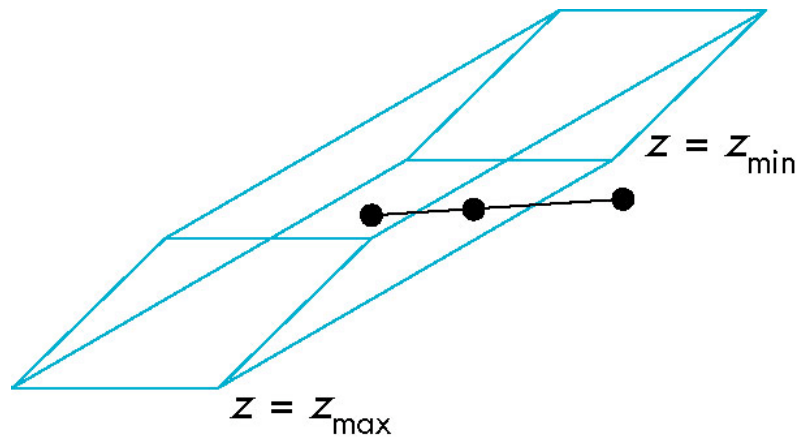
- Can accept/reject as easily as with Cohen-Sutherland
- Using values of  $\alpha$ , we do not have to use algorithm recursively as with C-S
- Extends to 3D



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# Clipping and Normalization

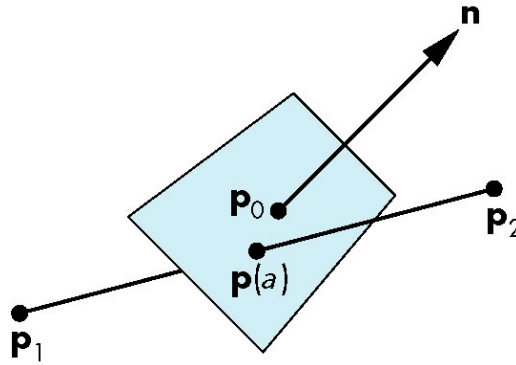
- General clipping in 3D requires intersection of line segments against arbitrary plane
- Example: oblique view





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# Plane-Line Intersections

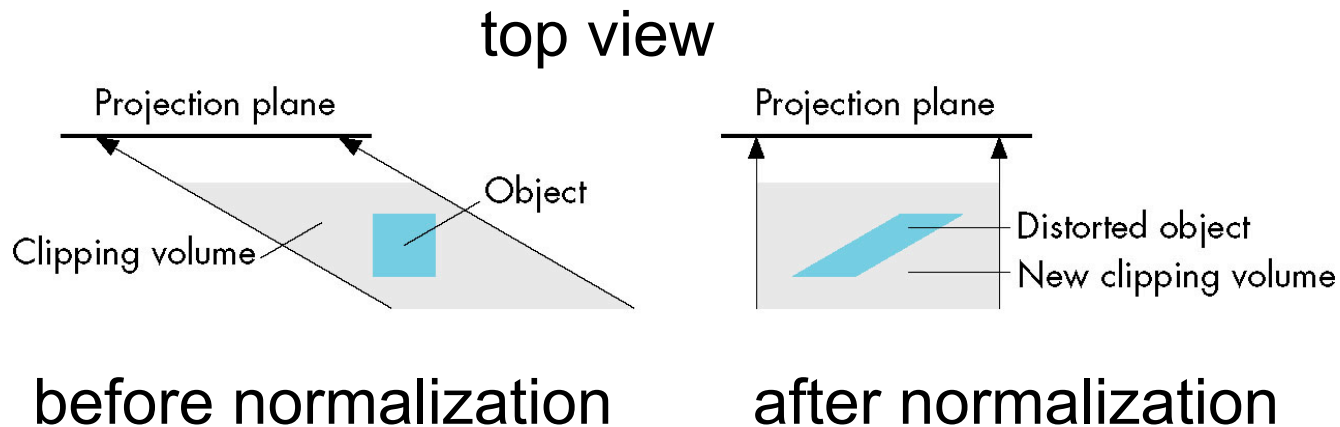


$$a = \frac{n \bullet (p_o - p_1)}{n \bullet (p_2 - p_1)}$$



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# Normalized Form



Normalization is part of viewing (pre clipping)  
but after normalization, we clip against sides of  
right parallelepiped

Typical intersection calculation now requires only  
a floating point subtraction, e.g. is  $x > x_{\max}$  ?