

CS 351

Design of Large Programs

Concurrency Control

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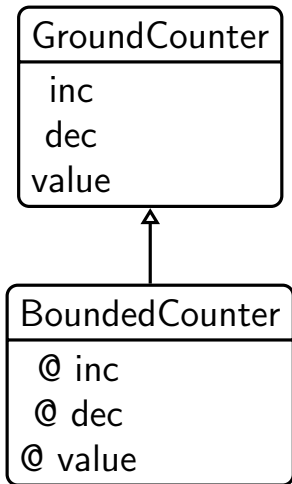
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Concurrency Control Definition

- Layering of synchronization and control policies over base mechanisms
- Key assumption: ground classes have been designed to be amenable to the desired forms of control
- Strategies
 - adding policy control in subclasses
 - controlling delegated actions
 - representing messages as objects

Adding Synchronization Via Subclassing

- Ground level class
 - provides non-public methods
 - enforces no invariants
- Subclass
 - implements the synchronization policy, e.g.,
 - atomic updates
 - bounded counter
 - delegates actions to ground methods



Bounded Counter Code

```
public class GroundCounter {
    protected long count;

    protected GroundCounter(long c) {
        count = c;
    }

    protected long value() { return count; }

    protected void inc() {
        ++count;
    }

    protected void dec() {
        --count;
    }
}
```

Bounded Counter Code

```
public class BoundedCounter extends GroundCounter {
    private final long MIN, MAX;

    public BoundedCounter(final long MIN, final long MAX) {
        super(MIN);
        this.MIN = MIN;
        this.MAX = MAX;
    }

    public synchronized long value() { return super.value(); }

    public synchronized void inc() {
        while (value() >= MAX) {
            try { wait(); } catch(InterruptedException e) {};
        }
        super.inc();
        notifyAll();
    }

    public synchronized void dec() {
        while (value() <= MIN) {
            try { wait(); } catch(InterruptedException e) {};
        }
        super.dec();
        notifyAll();
    }
}
```

Anomalies to be Avoided

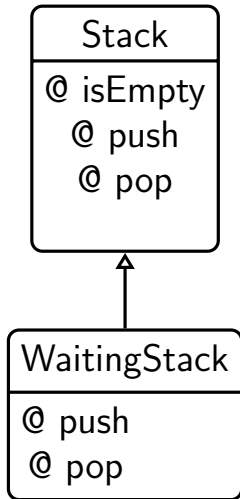
If all relevant variables and methods are declared **protected** the subclass can generally implement the desired policy

Frequent problems

- failing to track all conditions on which the subclass depends
- differences in state representation
- immutable variable in the superclass is being modified
- introducing waits for which the subclass has not matching notifications
- extensions which require a transition from `notify` to `notifyAll`

Layering Guards

- Ground level class
 - ensures atomicity
 - generates exception on empty stack
 - forces a busy wait solution in a concurrent setting
- Subclass
 - eliminates the exception generation
 - adopts a wait/notify protocol
 - delegates select actions to ground methods



Waiting Stack Code

```
public class Stack {
    public synchronized boolean isEmpty() { /* ... */ }
    public synchronized void push(Object x) { /* ... */ }
    public synchronized Object pop() throws StackEmptyException {
        if (isEmpty()) {
            throw new StackEmptyException();
        } else {
            // ...
        }
    }
}
```

```
public class WaitingStack extends Stack {
    public synchronized void push(Object x) {
        super.push(x);
        notifyAll();
    }

    public synchronized Object pop() throws StackEmptyException {
        while(isEmpty()) {
            try { wait(); } catch (InterruptedException e) {}
        }
        return super.pop();
    }
}
```


Conflict Sets et al

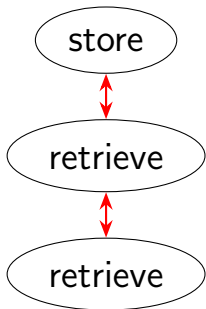
- Design paradigm
 - track the superclass state through the introduction of auxiliary variables
 - block method calls based on the current abstract state of the superclass
- Sample formalizations
 - conflict set
 - conflict graph
 - finite set control

Illustration: Inventory Control

Conflict Set

(store, retrieve)
(retrieve, retrieve)

Conflict Graph



Finite State control

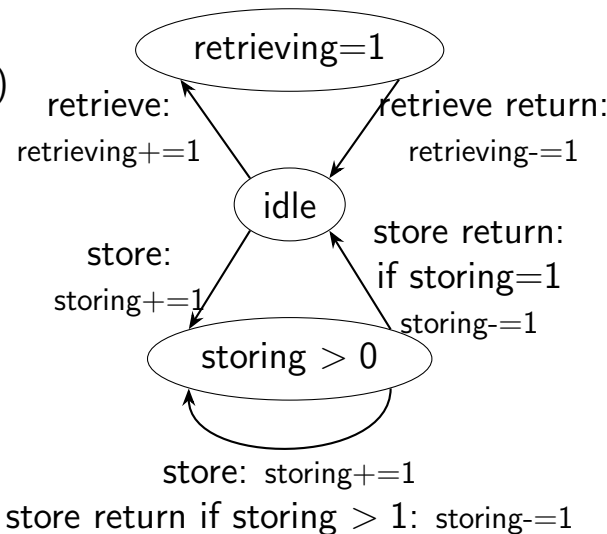


Illustration: Inventory Code

```
public class Inventory extends GroundInventory {
    protected int storing = 0;
    protected int retrieving = 0;

    public void store(String desc, Object item,
                     String supplier) {
        synchronized (this) {
            while (retrieving != 0) {
                try { wait(); } catch (InterruptedException e) {}
            }
            ++storing;
        }

        super.store(desc, item, supplier);

        synchronized (this) {
            if (--storing == 0) {
                notifyAll();
            }
        }
    }
}
```

Illustration: Inventory Code

```
public void retrieve(String desc, Object item,
                    String supplier) {
    synchronized (this) {
        while (storing != 0) {
            try { wait(); } catch (InterruptedException e) {
            }
            ++retrieving;
        }

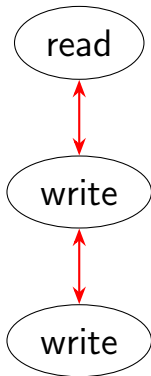
        super.retrieve(desc, item, supplier);

        synchronized (this) {
            if (--retrieving == 0) {
                notifyAll();
            }
        }
    }
}
```

Readers and Writers: A Common Design Pattern

- A simple conflict graph
- Readily ensured safety
- Major variations when it comes to liveness and lack of starvation

Conflict Graph



General Pattern

- Track the number of waiting and active readers and writers
- Bracket the read/write operations with before/after control code
- Same design accommodates a wide range of policies

General Pattern Code

```
public abstract class ReadWrite {
    protected int activeReaders = 0;
    protected int activeWriters = 0;
    protected int waitingReaders = 0;
    protected int waitingWriters = 0;

    protected abstract void doRead();
    protected abstract void doWrite();

    public void read() {
        beforeRead();
        doRead();
        afterRead();
    }

    public void write() {
        beforeWrite();
        doWrite();
        afterWrite();
    }
}
```

Control Code: before/afterRead

```
protected synchronized void beforeRead() {
    ++waitingReaders;
    while (!allowReader()) {
        try { wait(); } catch (InterruptedException e) {}
    }
    --waitingReaders;
    ++activeReaders;
}

protected synchronized void afterRead() {
    --activeReaders;
    notifyAll();
}
```


Control Code: before/afterWrite

```
protected synchronized void beforeWrite() {
    ++waitingWriters;
    while (!allowWriter()) {
        try { wait(); } catch (InterruptedException e) {}
    }
    --waitingWriters;
    ++activeWriters;
}

protected synchronized void afterWrite() {
    --activeWriters;
    notifyAll();
}
```

Policy: Reading Priority

- Direct enforcement of the conflict set rules
 - readers can read unless a writer is writing
 - a writer can start writing if no other thread is reading or writing
- Writers can be starved if readers continue to use the resource

```
protected boolean allowReader() {  
    return activeWriters == 0;  
}  
  
protected boolean allowWriter() {  
    return activeReaders == 0 && activeWriters == 0;  
}
```

Policy: Reading Preemption

- Writer starvation is prevented by blocking new reading threads once a writer is waiting
- Readers can be kept out by multiple writers waiting in line

```
protected boolean allowReader() {  
    return waitingWriters == 0 && activeWriters == 0;  
}  
  
protected boolean allowWriter() {  
    return activeReaders == 0 && activeWriters == 0;  
}
```

Policy: Turn Taking

- If both readers and writers are waiting, alternate between readers and writers
- Still, there is no guarantee that no readers or writers are blocked forever

Policy: Turn Taking

```
private boolean canWrite;

public synchronized void afterRead() {
    canWrite = true; // ...previous afterRead code...
}

public synchronized void afterWrite() {
    canWrite = false; // ...previous afterWrite code...
}

protected boolean allowReader() {
    if (waitingWriters > 0 && waitingReaders > 0) {
        return !canWrite && activeWriters == 0;
    }
    return waitingWriters == 0 && activeWriters == 0;
}

protected boolean allowWriter() {
    if (waitingWriters > 0 && waitingReaders > 0) {
        return canWrite && activeWriters == 0;
    }
    return activeReaders == 0 && activeWriters == 0;
}
```

Policy: Custom Scheduler

- Each reader/writer makes a request and gets a ticket number
- Each request and its type (read/write) is placed in a queue according with some policy that optimizes throughput and ensures fairness
- A writer starts working when its ticket is first in the queue
- A reader starts working when its ticket is part of a sequence of read requests at the front of the queue
- Tickets are returned upon completion of the operation
- Ticket counter is reset when no tickets are out

Basic Adapter Concept

- An *adapter* is a specialized wrapper that offers a new interface based on an existing class
- The main advantages are
 - flexibility
 - a range of services based on an existing class
 - dynamic changes of the base class in use
 - reduced coding effort
 - reuse of legacy code
- Adapters do not have access to protected fields and methods
 - this is distinct from subclassing

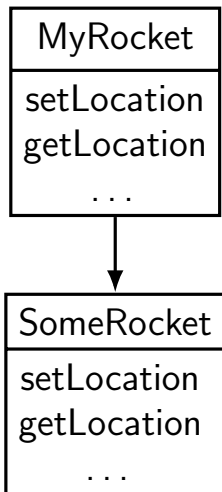
Example: Rocket

- Internal state
 - location (point in 3D space, meters)
 - velocity (3D vector, meters/sec)
 - flight time (seconds)
- Methods
 - read/update location
 - read/update velocity
 - increment flight time

Delegation

The interface is the same as that of the ground class

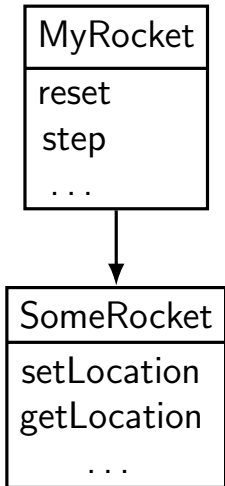
- actions are simply redirected
- returned values are passed up
- What is the gain?
 - flexibility



Refactoring

Different methods are provided and coded in terms of the ground class

```
public void reset() {  
    setFlightTime(0);  
    setLocation(new PosPoint());  
    setVelocity(new VelVec());  
}  
  
public void step(VelVec vel) {  
    flightTime++;  
    velocity = vel;  
    location.add(velocity);  
}
```



Superposition

Superposition – a process by which variables are introduced to monitor the state of the ground class

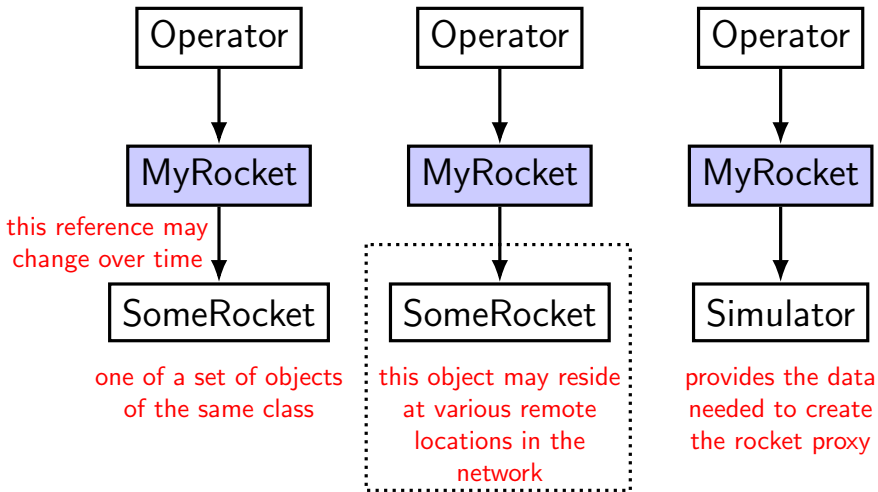
- to extend functionality without actually affecting the state
- to facilitate reasoning about the computation

```
public void step(VelVec vel) {  
    flightTime++;  
    velocity = vel;  
    location.add(velocity);  
    if(velocity.compare(MAX_SAFE_VEL) > 0) {  
        unsafeCount++;  
    }  
}
```

Proxy – A Useful Design Pattern

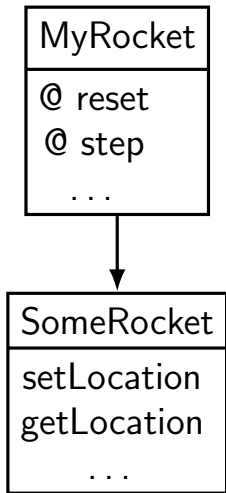
- Proxy – an object that stands in place of another
 - displays an appropriate veneer
 - delegates all actions
- The original object may be a
 - concrete object – present in the system and having the same interface
 - abstract object – the result of refactoring

Illustration: Proxy Examples



Synchronized Adapters

- In the presence of concurrency, objects designed to function in a single threaded environment need to be protected
- The wrapper can provide the needed synchronization (when the ground object is private)



Synchronized Adapters with Access Control

- An adapter can also introduce blocking of threads in a way that is sensitive to the state of the ground object
- Illustration: block thread waiting for a specific target velocity to be reached and release it when
 - a reset has been issued (return false)
 - the target velocity has been reached or exceeded (return true)

Synchronized Adapters with Access Control

```
public synchronized void step(VelVec vel) {
    // ...
    notifyAll();
}

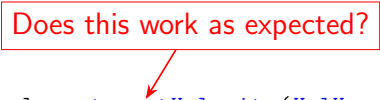
public synchronized void reset() {
    // ...
    notifyAll();
}

public synchronized boolean targetVelocity(VelVec vel) {
    // mag returns integer magnitude of vector
    while (mag(velocity) != 0 && mag(velocity) < mag(vel)) {
        try { wait(); } catch (InterruptedException e) { }
    }
    if(mag(velocity) == 0) return false; // reset issued
    else return true; // target velocity reached
}
```


Synchronized Adapters with Access Control

```
public synchronized void step(VelVec vel) {  
    // ...  
    notifyAll();  
}  
  
public synchronized void reset() {  
    // ...  
    notifyAll();  
}  
  
public synchronized boolean targetVelocity(VelVec vel) {  
    // mag returns integer magnitude of vector  
    while (mag(velocity) != 0 && mag(velocity) < mag(vel)) {  
        try { wait(); } catch (InterruptedException e) { }  
    }  
    if(mag(velocity) == 0) return false; // reset issued  
    else return true; // target velocity reached  
}
```

Does this work as expected?



What's wrong?

When `notifyAll` is invoked in a synchronized method M_1 :

1. An arbitrarily chosen waiting thread T is removed from the waiting set
2. T blocks while re-obtaining the lock
 - T blocks AT LEAST until M_1 releases the lock – if another synchronized method M_2 acquires the lock first, T continues to block!
3. T resumes from the point of wait

A thread in step may change shared state before T resumes from the wait in `targetVelocity`!

Synchronized Adapters with Access Control

```
public synchronized void step(VelVec vel) {
    // ...
    notifyAll();
}

public synchronized void reset() {
    // ...
    tracking = false;
    notifyAll();
}

public synchronized boolean targetVelocity(VelVec vel) {
    tracking = true; // remains true unless reset
    while (tracking && mag(velocity) < mag(vel)) {
        try { wait(); } catch (InterruptedException e) { }
    }
    if(!tracking) return false;
    tracking = false;
    return true;
}
```

Extending Atomicity

- An adapter can augment existing methods with additional functionality while making the entire operation atomic
- Illustration: augment the step method to include a logging action

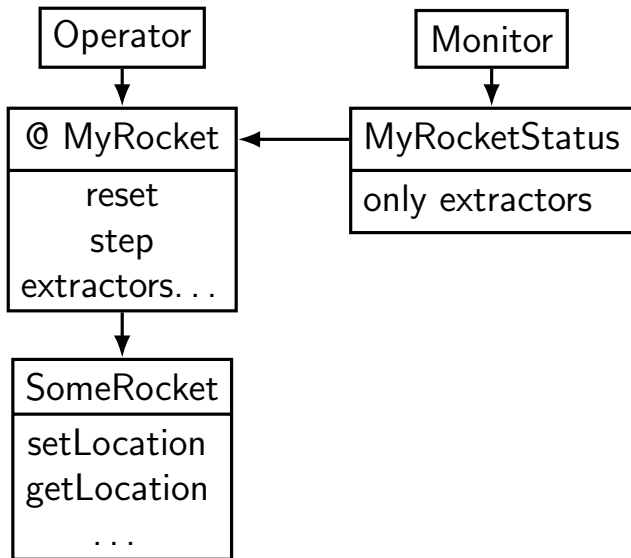
```
public synchronized void step(VelVec vel) {
    flightTime++;
    velocity = vel;
    location.add(velocity);
    Log.addEntry(flightTime, location);
}

class Log {
    public static synchronized void addEntry(int time,
                                              PosPoint loc) {
        // store/print entry...
    }
}
```

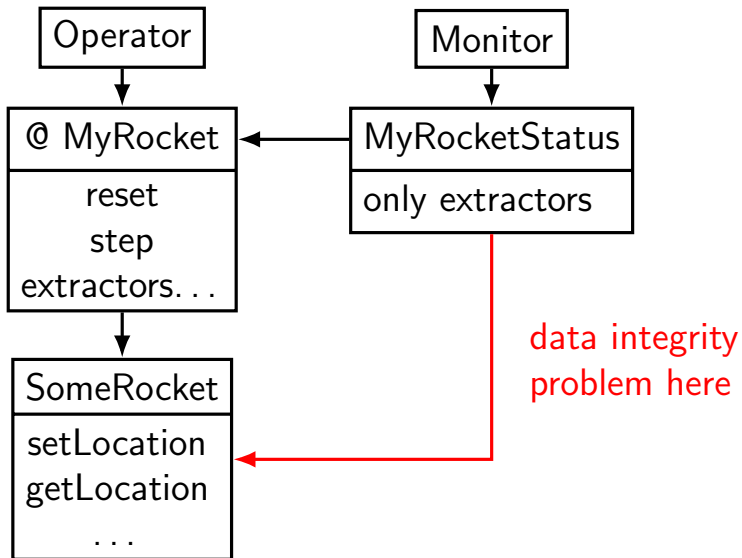
Read Only Adapters

- It is often the case that data needs to be protected against unauthorized modification
- A read-only wrapper gives full access to the object data without the risk of being modified

Read Only Adapters



Read Only Adapters



Programming Concerns

- The methods of the immutable object should be declared final
- The base object B should not be leaked to users of the immutable object X

```
public final class MyRocketStatus {
    private final int flightTime;
    private final PosPoint location;
    public MyRocketStatus(MyRocket rocket) {
        flightTime = rocket.getFlightTime();
        location = rocket.getLocation();
    }
    public int getFlightTime() { return flightTime; }
    public PosPoint getLocation() { return location; }
}

public class Log {
    public static synchronized void addEntry(MyRocketStatus stat) {
        // store/print status...
    }
}
```


Acceptor

- receives requests in the form of messages
- interprets the messages within the context of a system
- by considering pending requests
- by analyzing the program state
- by enforcing execution rules
- initiates actions performed by underlying ground objects

```
public interface Acceptor {  
    public void accept(MessageType m);  
}
```

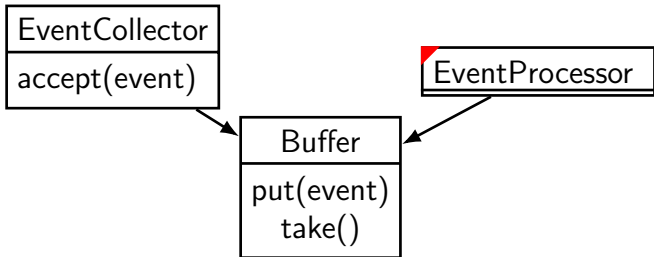
Design Strategies

- An acceptor may
 - employ its own private ground objects
 - delegate actions to ground objects
 - employ a dispatch table
 - generate a thread for each response
 - maintain state information
 - schedule multiple agents
 - maintain history logs
 - filter and modify messages
- Acceptors may work in tandem

Event Loops

Key concepts and components

- event – the class of messages accepted
- buffer – holder of messages to be processed
- collector – recipient of events and known to event producers
- processor – event dispatcher knowing the ground objects



Sample Code Using Bounded Buffer

```
public class EventCollector implements Acceptor {
    protected BlockingQueue<Event> buff;

    public EventCollector() {
        buff = new ArrayBlockingQueue<>(100);
        new EventProcessor(buff);
    }

    public synchronized void accept(Event e) {
        buff.put(e);
    }
}
```

Sample Code Using Bounded Buffer

```
public class EventProcessor implements Runnable, Acceptor {
    protected BlockingQueue<Event> buff;
    public EventProcessor(BlockingQueue<Event> b) {
        buff = b;
        new Thread(this).start();
    }

    public void run() {
        while (true) {
            accept(buff.take());
        }
    }

    public void accept(Event e) {
        switch (e.eventCode()) {
            // dispatch...
        }
    }
}
```